User's Manual

Model VJH7 JUXT/ Isolator (Multi-function)

(Isolated Single-output and Isolated Dual-output Types)

Thank you for purchasing the JUXTA Signal Conditioner. Please read through this manual before use for correct handling.



IM 77J01H07-01E 1st Edition Nov. 1999 4th Edition Feb. 2017

Yokogawa Electric Corporation

CAUTIONARY NOTES FOR SAFE USE OF THE PRODUCT

This User's Manual should be carefully read before installing and operating the product. Please keep this User's Manual for future reference.

For more information of the safety precautions, please refer to the "Precautions on the Use of the JUXTA Series (IM 77J01A00-91Z1)". The related manuals and general specifications are shown in the table below.

Doc. Name	Doc. Number
Precautions on the Use of the JUXTA Series (User's Manual)	IM 77J01A00-91Z1
Model VJH7 Isolator (User's Manual)	IM 77J01H07-01E
	(This manual)
Model VJH7 Isolator (General Specifications)	GS 77J01H07-01E

User's manuals in the above table are essential parts of the product; keep it in a safe place for future reference.

This manual is intended for the following personnel;

- Engineers responsible for installation, wiring, and maintenance of the equipment.
- Personnel responsible for normal daily operation of the equipment.

The following symbol is used on the product and in this manual to ensure safe usage.



WARNING

Calls attention to actions or conditions that could cause serious or fatal injury to the user, and indicates precautions that should be taken to prevent such occurrences.



CAUTION

Calls attention to actions or conditions that could cause injury to the user or damage to the instrument or property and indicates precautions that should be taken to prevent such occurrences.

CHECKING PRODUCT SPECIFICATIONS AND THE CONTENTS OF PACKING

(1) Model Number and Specification Check

Check that the model number and specifications shown on the nameplate attached on the side of the product are as ordered.

(2) Contents of the Packing

Check that the packing contains the following items:

VJH7: 1 unit

Standard Accessories:

- Tag number label: 1 sheet
- · Range label: 1 sheet
- Shunt registor (for specification of current input): 1 piece
- User's manual (IM 77J01H07-01E, this manual): 1 copy
- User's manual (IM 77J01A00-91Z1): 1 copy

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You can download the latest manuals from the following website

http://www.yokogawa.com/ns/juxta/im/

GENERAL

This plug-in isolator, which belongs to the JUXTA series of signal conditioners, receives DC current or voltage signals and converts them to pairs of isolated DC voltage or current signals.

- Output-2 signal is selectable from a DC voltage signal, DC current signal, communication function (RS-485), and alarm output (two relay contacts). (Isolated Dual-output Type)
- Various parameters such as input range can be set and modified using a PC (VJ77(sold separately)) or Handy Terminal (JHT200(sold separately) and the like).

MODEL AND SUFFIX CODES

Model	Suffix codes					Description				
VJH7	-0	х	х	-x	х	х	0	/x	Isolator (Multi-function)	
Fixed code	-0								Always -0	
Output	Output 1							1 output		
configurati	configuration 2							2 outputs		
Dawar ayanlı							100-240 V AC/DC*1			
rower sup	Power supply 7							15-30 V DC ⁺²		
		_{-A}					0 to 50 mA DC, span is 5 mA or			
Input signa	Input cianal		-A					more		
iliput signal		-1					-10 to +10 V DC, span is 0.1 V			
							or more			
A 4 to 20 mA DC		4 to 20 mA DC								
Output-1 signal 6					1 to 5 V DC					
	Z (Custom order)*3		(Custom order)*3							
					Α			4 to 20 mA DC		
	6					1 to 5 V DC				
Output-2 s	igna	al				Р			Communication function (RS485)	
T			Т				Alarm output (2 relay contacts)			
					No output-2					
Fixed code	Fixed code 0			Always 0						
Option				/SN	No socket (with socket if not specified)					
				/C0	HumiSeal coating*4					
				/FB	Fuse bypass*4					

- *1: Operating range: 85 to 264V AC/DC
- *2: Operating range: 12 to 36V DC
- *3: DC voltage signal or DC current signal
- *4: When option code /C0 or /FB is specified, the conformity to the safety and EMC standards is excluded. CE marking is not applicable.

1. MOUNTING METHODS

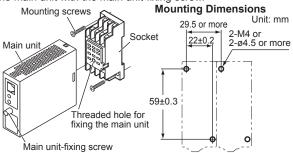


CAUTION

- Plug/disconnect the main unit into/from the socket vertically to the socket face. Otherwise the terminals may bend and it may cause bad contact.
- The converter shall not tilt 5 degrees or more in either direction when installed.
- When the converter is not connected to the socket, it is necessary to protect the socket against ingress of dust to the connector part.
- Keep this product in a conductive bag when plugged out, during transport or storage.

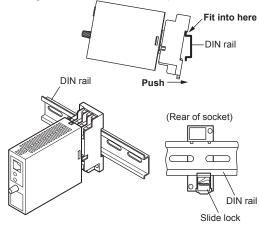
1.1 Wall Mounting

Loosen the main unit-fixing screw of the isolator to disconnect the main unit from the socket. Next, anchor the socket onto the wall with screws. Then, plug the main unit into the socket and secure the main unit with the main unit-fixing screw.



1.2 DIN Rail Mounting

Locate the isolator so that the DIN rail fits into the upper part of the DIN-rail groove at the rear of the socket, and fasten the socket using the slide lock at the lower part of the socket.



1.3 Mounting Using a Multi-mounting Base

For mounting using a multi-mounting base, see the Instruction Manual for VJCE (VJ Mounting Base).

1.4 Using Ducts

Wiring ducts should be installed at least 30 mm away from the top or bottom of the main unit.

2. INSTALLATION LOCATION

- Avoid the following environments for installation locations: Areas with vibrations, corrosive gases, dust, water, oil, solvents, direct sunlight, radiation, a strong electric field, and/or a strong magnetic field, direct radiant heat, wind, temperature fluctuation, 2,000 m or more above sea level.
- If there is any risk of a surge being induced into the power line and/or signal lines due to lightning or other factors, a dedicated lightning arrester should be used as protection for both the product and a field-installed device.
- Operating temperature/humidity range: -10 to 55°C (-10 to 45°C for side-by-side mounting*)/5 to 90%RH (no condensation)
 - * If the previous model (style S3.xx earlier) is installed together, the ambient temperature is 0 to 40°C.
- Continuous vibration: (at 5 to 9 Hz) Half amplitude of 3 mm or less (at 9 to 150 Hz) 9.8m/s² or less, 1 oct/min for 90 minutes each in the three axis directions
- Impact: 98 m/s2 or less, 11 ms, 3 axes, 6 directions, 3 times each

3. EXTERNAL WIRING



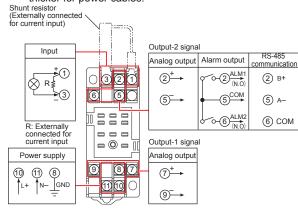
WARNING

- To avoid the risk of an electric shock, turn off the power supply and use a tester or similar device to ensure that no power is supplied to a cable to be connected, before carrying out wiring work.
- Do not operate the product in the presence of flammable or explosive gases or vapors. To do so is highly dangerous.

- Use of the product ignoring the specifications may cause overheating or damage. Before turning on the power, ensure the following:
 - Power supply voltage and input signal value applied to the product should meet the required specifications.
 - The external wiring to the terminals and wiring to ground are as specifications.

Wiring should be connected to the terminals on the socket of the product. The terminals for external connections are of M3 screws. Use crimp-on terminal lugs for connections to the terminals.

 Recommended cables: A nominal cross-sectional area of 0.5 mm² or thicker for signal cables, and that of 1.25 mm² or thicker for power cables.





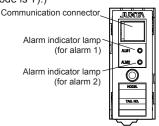
CAUTION

- Do not use output-2 for the isolated single-output type.
- The power line and input/output signal lines should be installed away from noise-generating sources.
 Other wise accuracy cannot be guaranteed.
- Make sure to earth ground the ground terminal through minimum resistance. The length and thickness of the grounding cable should be as short and thick as possible. Directly connect the lead from the ground terminal (terminal no. 8) of the product to the ground. Do not carry out daisychained inter-ground terminal wiring.
- The product is sensitive to static electricity; exercise care in operating it. Before you operate the product, touch a nearby metal part to discharge static electricity.
- The use of inductance (L) loads such as auxiliary relays and solenoid valves causes malfunction or relay failure; always insert a CR filter or diode for spark-removal into the line in parallel with the load. Recommended CR
 - C: 0.5 to 1µF against contact current 1A
 - R: 0.5 to 1Ω against contact voltage 1V
- If the ambient temperature is 50 °C or more, please use the cable that the rated temperature is 70 °C or

4. DESCRIPTION OF FRONT PANEL AND CONNECTION OF HANDY TERMINAL

4.1 Front Panel

The communications connector in the front panel is used for setting up parameters through the Handy Terminal. The alarm-1 and alarm-2 LEDs light up if an alarm occurs (those LEDs are provided only when the output-2 is specified for alarm output (the output-2 suffix code is T).)

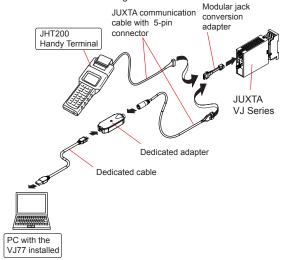


4.2 Connecting the Handy Terminal

Use the connector for communication when setting the parameters using a PC (VJ77 Parameters Setting Tool) or the Handy Terminal.

< How to connect with the setting tool>

<How to connect with the setting tool>



- Use the VJ77 of version R2.02.01 or later.
- The modular jack conversion adapter does not come with the JHT200 Handy Terminal. It is sold separately.

SETTING PARAMETERS

Set the parameters using a PC (VJ77 Parameter Setting Tool) or the Handy Terminal. Refer to "7. LIST OF PARAMETERS" in this manual and the User's Manual for VJ77 PC-based Parameters Setting Tool (IM 77J01J77-01E) or the User's Manual for JHT200 Handy Terminal (IM 77J50H01-01EN).

5.1 Settings Related to Inputs and Outputs

5.1.1 Input Type

Set by selecting input type from among VOLTS (DC voltage) and CURRENT (DC current) in [D12: INP TYPE].

5.1.2 Input Range

Set the 0% value of input range to [D24: INPUT1 L_RNG] and the 100% value of input range to [D25: INPUT1 H_RNG] within the numerically specified range.



In case the input range is changed after factory-ship, the instrument may not work within the rated accuracy range depending on the changed input range. Perform the adjustment following the maintenance of this instruction manual after changing the input range.

5.1.3 Software Filter

Set the software filter in [D57: S/W FILTER]. OFF, LOW, MIDDLE, HIGH (default value: OFF) When LOW, MIDDLE, or HIGH is selected, a first-order filter equivalent to 100 ms, 300 ms, or 1 s is inserted in the input.

5.1.4 Direction of Output Action

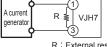
Analog output signals can be reversed. To reverse the signal from output-1, set [D50: OUT1 DR] to REVERSE. For output-2, set [D51 OUT2 DR] to REVERSE. To return the output-1 signal to normal, set [D50: OUT1 DR] to DIRECT. For output-2, set [D51: OUT2 DR] to DIRECT

5.1.5 External Input Resistance Correction

For current input, set the external resistance to [D13: IN RESIST]. There is a difference between this value and the actual external resistance. If this difference causes an error, the input can be corrected.

To perform correction, wire as shown in the figure below, apply a stable input equivalent to 100%, and set [P40:RESISTOR ADJ1 to EXECUTE.

If you need perform correction again such as when the external resistance is changed, reset the correct value. To do so, set **[P40: RESISTOR ADJ]** to RESET.



R: External resistor

5.2 Settings Related to Communication **Function**

Set the following parameters when output-2 is specified for communication function. For more information on the communication function, see the Instruction Manual for VJ Series Communication Function (IM 77J1J11-01E).

5.2.1 Communication Protocol

Set the communication protocol by selecting from among PC-LINK, PC-LINK WITH SUM, MODBUS ASCII, MODBUS RTU, and LADDER in [F01: PROTOCOL].

5.2.2 Communication Address

Set the address number of the isolator numerically in a range of 1 to 99 in [F02: ADDRESS].

5.2.3 Baud Rate

Set the baud rate by selecting from among 1200, 2400, 4800, 9600, 19200 and 38400 bps in [F03: BAUD RATE].

5.2.4 Parity

Select and set NONE, EVEN, or ODD in [F04: PARITY].

5.2.5 Data Length

Select and set 7 bits or 8 bits in [F05: DATA LEN].

5.2.6 Stop Bit

Select and set 1 bit or 2 bits in [F06: STOP BIT]

Input Decimal Point Position

Number of digits of decimal places (setting of D register [D0003]) can be set.

Select and set among 0 to 5 digits in [F07: INPUT DEC PT].

5.3 Settings Related to Alarm Output

Set the following parameters when output-2 is specified for alarm

5.3.1 Alarm Setpoints

Set the alarm setpoints of alarm-1 and alarm-2 in [E03: SET POINT1] and [E04: SET POINT2] numerically.

- Setting range: A range of 0 to 100% of input range
- Setting resolution: 0.1%

5.3.2 Direction of Alarm Action

Select the direction of alarm-1 action and that of alarm-2 action from among HIGH ALM (high-limit alarm) and LOW ALM (low-limit alarm) and set each in [E05: ALM1 ACTION] (direction of alarm-1 action) or [E06: ALM2 ACTION] (direction of alarm-2 action).

- To activate alarm status when input signal ≥ alarm setpoint, select HIGH ALM.
- To activate alarm status when input signal ≤ alarm setpoint, select LOW ALM.

5.3.3 Hysteresis

Set alarm-1 and alarm-2 hysteresis, in [E09: HYSTERESIS1] and [E10: HYSTERESIS2]. Hysteresis is a value added to the alarm setpoint in order for an alarm status to be released (to normal) after the alarm status has been activated. The alarm status will be released in the following conditions, depending on the direction of alarm action.

- When HIGH ALM (high-limit alarm) is set: Alarm is released when input signal < (alarm setpoint - hysteresis).
- When LOW ALM (low-limit alarm) is set: Alarm is released when input signal > (alarm setpoint + hysteresis).
- Setting range: A range of 0 to 100% of input range
- Setting resolution: 0.1%

Alarm ON Delay and Alarm OFF Delay

Set alarm-1 and alarm-2 ON delays in [E11: ON DELAY1] and [E12: ON DELAY2] and then alarm-1 and alarm-2 OFF delays in [E13: OFF DELAY1] and [E14: OFF DELAY2].

An alarm ON delay is a delay time from the establishment of alarm condition to alarm output; an alarm OFF delay is a delay time from the establishment of return-to-normal condition to output.

- Setting range: 0 to 999 seconds
- Setting resolution: 1 second (Note that about 0.2 second will be added to set time to prevent erroneous operation.)

For example, when an alarm ON delay is set to 1 second, alarm output is generated if alarm status continues for more than 1 second after the input value exceeds the alarm setpoint. Further, when an alarm OFF delay is set to 2 seconds, alarm output is released if normal condition continues for more than 2 seconds after the input value has returned to normal from the alarm status

5.3.5 Direction of Relay Action

Set the direction of relay energizing in alarm-1 normal condition and alarm-2 normal condition by selecting from among NRM DE-ENERGIZED (de-energized under normal condition) and NRM ENERGIZED (energized under normal condition) in [E15: RL1 ACTION] and [E16: RL2 ACTION] and set them.

DESCRIPTION OF ALARM ACTIONS

This chapter describes examples of alarm actions under the following conditions.

Item	Alarm 1		Alarm 2		
	Parameter	Setpoint	Parameter	Setpoint	
Direction of alarm action	E05: ALM1 ACTION	High-limit alarm	E06: ALM2 ACTION	Low-limit alarm	
Alarm setting	E03: SET POINT1	80%	E04 : SET POINT2	15%	
Hysteresis	E09: HYSTERESIS1	10%	E10: HYSTERESIS2	5%	
Alarm ON delay	E11: ON DELAY1	1 sec	E12 : ON DELAY2	3 sec	
Alarm OFF delay	E13: OFF DELAY1	2 sec	E14 : OFF DELAY2	4 sec	
Description of alarm actions	condition where the input value is 80% or more of high-limit alarm continues for 1 second or more. After the alarm is output, when the condition where the input value is less than 70% of high-limit alarm continues for 2 seconds or more, the status		The alarm is output if the condition where the input value is 15% or less of low-limit alarm continues for 3 seconds or more. After the alarm is output, when the condition where the input value is more than 20% of low-limit alarm continues for 4 seconds or more, the status returns to normal.		

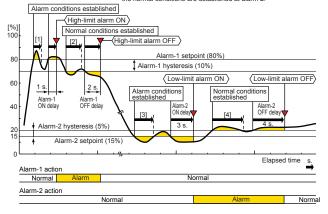
Figure 6.1

- [1] Alarm status does not continue for more than 1 second after the alarm conditions are established at alarm 1.

 [2] Normal status does not continue for more than 2 seconds after the normal conditions are established at alarm 1.

 [3] Alarm status does not continue for more than 3 seconds after the alarm conditions are established at alarm 2.

 [4] Normal status does not continue for more than 4 seconds after the normal conditions are setablished at later 2.
- the normal conditions are established at alarm 2.



LIST OF PARAMETERS

	Baramatar Dianlay	Itam	
	MODEL	Model Model	
	TAG NO	Tag no.	
	SELF CHK	Self-check result	
Α	DISPLAY1	Display1	*2
A01	INPUT1	Input value 1	
A09	OUTPUT1	Output value 1	
A10	OUTPUT2	Output value 2	
A15 A16	ALM1 STATUS ALM2 STATUS	Alarm-1 status Alarm-2 status	
A54	STATUS	Status	*1
A56	REV NO	Rev. no.	
A58	MENU REV	MENU REV	
A60 B	SELF CHK DISPLAY2	Self-check result	*2
B01	INPUT1	Display2 Input value 1	
B09	OUTPUT1	Output value 1	
B10	OUTPUT2	Output value 2	
B15	ALM1 STATUS	Alarm-1 status	
B16	ALM2 STATUS	Alarm-2 status	
B60	SELF CHK SET (I/O)	Self-check result Setting (I/O)	*2
D01	TAG NO.1	Tag no. 1	
D02	TAG NO.2	Tag no. 2	
D03	COMMENT1	Comment 1	
D04	COMMENT2	Comment 2	
D12	INP TYPE	Input type	
D13 D24	IN RESIST INPUT1 L RNG	Input resistance Input low range	
D25	INPUT1 H RNG	Input high range	
D32	OUT1 L_RNG	Output-1 low range	*3
D33	OUT1 H_RNG	Output-1 high range	*3
D34	OUT2 L_RNG	Output-2 low range	*3
D35	OUT2 H_RNG	Output-2 high range	*3
D50 D51	OUT1 DR OUT2 DR	Direction of output-1 action Direction of output-1 action	
D57	S/W FILTER	Software filter	
D59	NMRR	Frequency setting	*3
D60	SELF CHK	Self-check result	
E	SET(ALM)	Setting (alarm output)	*2
E E03	SET POINT1	Alarm-1 setting (%)	*2
E E03 E04	SET POINT1 SET POINT2	Alarm-1 setting (%) Alarm-2 setting (%)	*2
E E03	SET POINT1	Alarm-1 setting (%)	*2
E03 E04 E05 E06 E09	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action	*2
E03 E04 E05 E06 E09 E10	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%)	*2
E E03 E04 E05 E06 E09 E10 E11	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting	*2
E03 E04 E05 E06 E09 E10 E11 E12	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting	*2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-1 OFF delay setting	*2
E03 E04 E05 E06 E09 E10 E11 E12	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting	*2
E03 E04 E05 E06 E09 E10 E11 E12 E13 E14 E15 E16	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-1 OFF delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action	*2
E03 E04 E05 E06 E09 E10 E11 E12 E13 E14 E15 E16 E60	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result	
E03 E04 E05 E06 E09 E10 E11 E12 E13 E14 E15 E16 E60	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM)	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication)	*2
E03 E04 E05 E06 E09 E10 E11 E12 E13 E14 E15 E16 E60 F	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol	
E03 E04 E05 E06 E09 E10 E11 E12 E13 E14 E15 E16 E60	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM)	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication)	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-1 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit	
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1	**2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ IN1 SPAN ADJ	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of input-1	**2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 SPAN ADJ OUT1ZERO ADJ	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-1 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1	**2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY1 OFF DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ IN1 SPAN ADJ OUT1SPAN ADJ	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 ON delay setting Alarm-2 ON delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1	**2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY1 OFF DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ IN1 SPAN ADJ OUT1SPAN ADJ OUT1SPAN ADJ OUT1SPAN ADJ	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 ON delay setting Alarm-2 ON delay setting Alarm-1 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1 Zero adjustment of output-1	**2
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E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY1 OF DELAY1 OFF DELAY1	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1 Span adjustment of output-2 Span adjustment of output-2 Adjustment of external input resistance Self-check result Test	**2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY1 OF DELAY1 OFF DELAY1 NALE SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ SELF CHK TEST OUT1 TEST	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-1 OFF delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1 Span adjustment of output-2 Adjustment of output-2 Adjustment of output-2 Adjustment of output-1 Test Forced output (output-1)	*2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY1 OFF DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1SPAN ADJ OUT2SPAN ADJ RESISTOR ADJ SELF CHK TEST OUT1 TEST	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1 Zero adjustment of output-2 Span adjustment of output-2 Adjustment of external input resistance Self-check result Test Forced output (output-1) Forced output (output-2)	*2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY1 OFF DELAY2 RL1 ACTION RL2 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ IN1 SPAN ADJ OUT1ZERO ADJ SELF CHK TEST OUT1 TEST	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Zero adjustment of output-1 Span adjustment of output-2 Span adjustment of output-2 Adjustment of external input resistance Self-check result Forced output (output-1) Forced output (output-2) Forced output (alarm 1)	*2
E E E E E E E E E E E E E E E E E E E	SET POINT1 SET POINT2 ALM1 ACTION ALM2 ACTION HYSTERESIS1 HYSTERESIS2 ON DELAY1 ON DELAY2 OFF DELAY2 RL1 ACTION RL2 ACTION RL2 ACTION RL2 ACTION SELF CHK SET(COM) PROTOCOL ADDRESS BAUD RATE PARITY DATA LEN STOP BIT INPUT DEC PT SELF CHK ADJUST IN1 ZERO ADJ IN1 SPAN ADJ OUT1ZERO ADJ OUT1ZERO ADJ OUT1SPAN ADJ OUT2SPAN ADJ OUT2SPAN ADJ SELF CHK TEST OUT1 TEST OUT2 TEST ALM1 TEST ALM2 TEST SELF CHK	Alarm-1 setting (%) Alarm-2 setting (%) Direction of alarm-1 action Direction of alarm-2 action Alarm-1 hysteresis (%) Alarm-2 hysteresis (%) Alarm-2 hysteresis (%) Alarm-1 ON delay setting Alarm-2 ON delay setting Alarm-2 OFF delay setting Direction of alarm-1 relay action Direction of alarm-1 relay action Direction of alarm-1 relay action Self-check result Setting (communication) Communication protocol Address Baud rate Parity Data Length Stop bit Decimal point position of input Self-check result Adjustment Zero adjustment of input-1 Span adjustment of output-1 Span adjustment of output-1 Zero adjustment of output-2 Span adjustment of output-2 Adjustment of external input resistance Self-check result Test Forced output (output-1) Forced output (output-2)	*2

- *2 There are items not displayed depending on what output-2 is
- *3 The parameters are the items to be set at the factory.

MAINTENANCE

The product starts running immediately when the power is turned on; however, it needs 10 to 15 minutes of warm-up before it meets the specified performance.

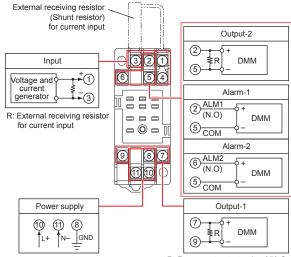
For cleaning the instrument, use a soft and dry cloth.

8.1 Calibration Apparatus

- A voltage and current generator (YOKOGAWA GS200 or the equivalent)
- Digital Multimeter (YOKOGAWA 7561 or equivalent): 1
- A precision resistor of 250 Ω ± 0.01%, 1 W (for current output)
- Setting tool for adjustment (Refer to "4.2 Connecting the Setting Tools" in this manual.)

8.2 Calibration Procedure

1. Connect the instruments as shown in figure below. First adjust the output-1 signal and then the output-2 signal.



R: For current output using 250 Ω precision resistor

- 2. Produce input signals equivalent to 0, 25, 50, 75, and 100% of the input span from the voltage and current generator to the isolator.
- 3. Then, check that the isolator's output signal shows voltages corresponding to 0, 25, 50, 75, and 100% of the input span within the rated accuracy range.

For alarm output, check the relay action by the alarm indicator lamp or resistance of output terminals.

If the output signal is out of the rated accuracy range, adjust the output signal level using the Handy Terminal (JHT200).

For adjustment using a setting tool, refer to the User's Manual for each setting tool and "7. List of Parameters" in this manual. User's Manual for VJ77 [Document No.: IM 77J01J77-01E]: User's Manual for JHT200 [Document No.: IM 77J50H01-01EN]

SAFETY AND EMC STANDARDS

The following will be acquired. Safety:

IEC/EN 61010-1 compliance (CE), IEC/EN 61010-2-030 compliance (CE)

CAN/CSA C22.2 No.61010-1 compliance (CSA)

UL61010-1 (CSA NRTL/C)

Installation category II

Pollution degree 2

Measurement category O (other)

Rated measurement input voltage: ±10 V DC max.

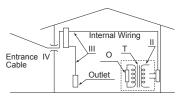
Rated transient overvoltage: 1500 V (*)

This is a reference safety standard value for Measurement Category I of CSA/UL61010-1 and Measurement Category O of EN 61010-2-030. This value is not necessarily a guarantee of instrument performance.



CAUTION

This instrument is for Measurement Category O (other). Do not use it for measurements in locations falling under Measurement Categories II, III, and IV.



Measurement category		Description	Remarks	
0	(other)	For measurements performed on circuits not directly connected to MAINS.		
II	CAT.II	For measurements performed on circuits directly connected to the low-voltage installation.	Appliances, portable equipments, etc.	
III	CAT.III	For measurements performed in the building installation.	Distribution board, circuit breaker, etc.	
IV	CAT.IV	For measurements performed at the source of the low-voltage installation.	Overhead wire, cable systems, etc.	

EMC standards:

CE marking:

EN 61326-1 Class A, Table 2 EN 61326-2-3

The instrument continues to operate at a measurement accuracy of within ±20% of the range during testing

EN 55011 Class A Group 1

EN 61000-3-2 Class A

EN 61000-3-3

EMC Regulatory Arrangement in Australia and New Zealand (RCM):

EN 55011 Class A, Group 1

KC marking:

Electromagnetic wave interference prevention standard, electromagnetic wave protection standard compliance



CAUTION

Caution to comply with EMC standards: When operating this instrument by external power supply, use an independent power unit conforming to CEmarking. Be sure to use the lightning arrester to comply EMC standards.

Note: When option code /C0 or /FB is specified, the conformity to the safety and EMC standards is excluded.

ENVIRONMENT STANDARD

RoHS Directive: EN 50581

(However, when option code /C0 or /FB is specified, CE marking is not applicable because the product does not comply with the Safety and EMC standards.)

TRANSPORT AND STORAGE CONDITIONS

- Temperature: -25 to 70°C
- Temperature change rate: 20°C per hour or less
- Humidity: 5 to 95%RH (no condensation)



5

CAUTION

Keep this product in a conductive bag when plugged out, during transport or storage.