

AHS/AHM36

Flexible, smart, compact: Encoders for countless fields of application

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.

Advantages



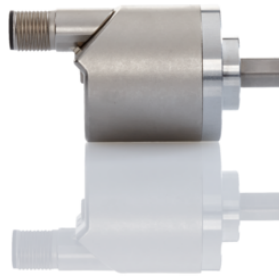
For encoders, flexibility is key

In order to provide maximum flexibility in the design of the mechanical interface, the AHS/AHM36 encoders are available with three different flange types (face mount flange, servo flange, blind hollow shaft), each with five different shaft diameters. Various assembly hole patterns are available in the face mount flange. A range of different pitch hole diameters are covered by the flexible stator coupling on the blind hollow shaft. And last but not least, a range of adapters guarantees compatibility with almost all absolute encoders with typical 60 mm flange designs. With the rotatable male connector or cable connection, the AHS/AHM36 can be integrated into the application in even the most limited of spaces and reduces the number of encoder variants when different installation situations are required.

Highest possible flexibility for the mechanical design



Various assembly hole patterns in the face mount flange



AHS/AHM36 with M12 male connector, rotated in axial direction



With the rotatable male connector or cable connection, the AHS/AHM36 can be integrated into the application in even the most limited of spaces and reduces the number of encoder variants when different installation situations are required.



Due to their compact size, the various flange types, adapter flanges and assembly hole patterns as well as the rotatable male connector or cable connection, the AHS/AHM36 devices can be integrated into virtually any application



Encoders for rough environments

The solution for applications with particularly harsh ambient conditions is AHS/AHM36 stainless steel Inox encoders. The housing, flange, shaft and stator coupling are made entirely of stainless steel (1.4305). Enclosure rating IP69K ensures additional impact protection which protects the shaft sealing ring installed in the encoder from the water jet of the shock blower.



AHS/AHM36 Inox with blind hollow shaft and cable connection



AHS/AHM36 Inox with face mount flange and M12 male connector



AHS/AHM36 Inox devices offer high resistance to environmental influences. With the IP69K enclosure rating, the encoders are suitable for use in machines that are regularly cleaned with high-pressure cleaners.



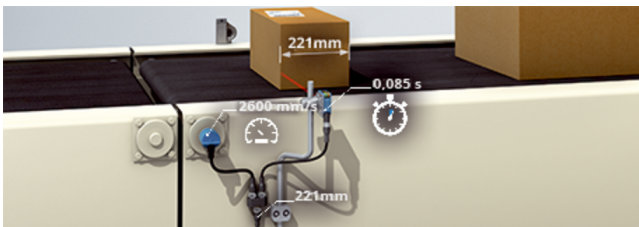
Advantages with IO-Link

IO-Link is a point-to-point communication protocol for connecting intelligent sensors and actuators within an automation network. SOPAS ET – the configuration software from SICK – allows IO-Link devices such as the AHS/AHM36 IO-Link to be easily visualized and parameterized. AHS/AHM36 IO-Link can be connected to any IO-Link master. The IO-Link offers a lot of benefits, e.g. automated storage of device parameters, unique device identification and the use of cost-efficient unshielded standard cables. In the Advanced and Inox versions, the AHS/AHM36 encoders offer extensive IO-Link functions, such as providing and storing diagnostic data (temperature, operating time, etc.), a configurable input and output pin, and integrated Smart Tasks, e.g. for length measurement. Thanks to their remote intelligence, these encoders provide the prerequisites for successful integration in more extensive edge computing concepts used for applications in Industry 4.0 and Smart Factory implementation.

Special versions of the AHS/AHM36 IO-Link include so-called Smart Tasks which enables them to make decentralized decisions and also carry them out autonomously. They take care of functions at the superordinate automation level, thereby improving response times because they reduce the communication load over the Ethernet and fieldbus networks. A wide variety of applications in which length measurement plays an important role can be designed more efficiently using Smart Tasks:

“Length measurement and trigger” Smart Task

- The IO-Link encoder measures and/or monitors the length of objects based on defined limit values, and outputs a signal when the length falls above or below these limits, for example in sorting processes in conveyor belt applications.
- The IO-Link encoder outputs a trigger when a pre-defined length has been reached. This Smart Task is used, for example, for cutting processes in the packaging and timber processing industries.



Measurement of object lengths and gaps between objects

The AHS/AHM36 IO-Link Advanced absolute encoder is suitable for measuring belt speeds. Thanks to the integrated A30 Smart Task, it can be combined with a photoelectric sensor to also detect the lengths of objects and the gaps between objects. Limit values can be defined for the latter which the encoder monitors.



Length measurement of packaging film

The AHS/AHM36 IO-Link Advanced absolute encoder, in combination with a print mark sensor, measures the exact length of packaging film. With the help of the integrated A30 Smart Task, after a set length value passes through, a trigger signal can be output with which the downstream cutting system is controlled for singulation of packaging films. Direct length measurement in the encoder also works precisely and reliably when conveying speeds change.



The AHS/AHM36 IO-Link Advanced and AHS/AHM36 IO-Link Inox encoders provide countless diagnostic data such as temperature values and operating hour counters

Thanks to remote intelligence, the AHS/AHM36 IO-Link can be successfully integrated into more comprehensive edge computing concepts when implementing Industry 4.0 and the Smart Factory.



The IO-Link interface enables cost-effective and easy integration of AHS/AHM36 devices into Ethernet and fieldbus networks. The provision and saving of diagnostic data, a configurable input and output pin and integrated Smart Tasks offer the user countless additional benefits.



Benefits of SSI and CANopen

The two established CANopen and SSI communication interfaces, with which the AHS/AHM36 encoders are available, also offer many advantages. Diagnostic data can be communicated as service data via the CANopen interface in addition to the process data position, speed and current temperature. For example, this includes the maximum speed, minimum and maximum temperature and the operating time. AHS/AHM36 CANopen can be configured either using the EDS file via the engineering tool of the respective control, or via the PGT-12-Pro hand-held programming tool from SICK. The programmable AHS/AHM36 SSI devices can be used both via the SICK SOPAS engineering tool or via the PGT-10-Pro hand-held programming tool. Various parameters such as the resolution, counting direction and code type can be customized according to the application. Even the structure of the SSI protocol to be output can be adapted so that the AHS/AHM36 encoders are compatible with virtually any SSI encoder.



In addition to the typical position and speed process data, the AHS/AHM36 CANopen can also output the current operating temperature of the encoder. Other diagnostic data can also be output.



The AHS/AHM36 CANopen and AHS/AHM36 SSI encoders can be configured easily and comprehensively via a hand-held programming tool



AHS/AHM36 SSI encoders can also be configured using the PC-based SICK SOPAS engineering tool



The AHS/AHM36 CANopen and AHS/AHM36 SSI encoders can be configured individually, making it possible to adjust them flexibly to nearly any application. Thanks to the compact, hand-held programming tools, this is done independently and without the installation of hard- or software.



Technical data overview

Encoder design	Singleturn / Multiturn (depending on type)								
Shaft type	Solid shaft, Servo flange Solid shaft, face mount flange Blind hollow shaft								
Shaft diameter	<table border="0"> <tr> <td style="padding-right: 20px;">Solid shaft, Servo flange</td> <td>6 mm 8 mm 10 mm 1/4" 3/8" 6 mm ¹⁾</td> </tr> <tr> <td style="padding-right: 20px;">Solid shaft, face mount flange</td> <td>6 mm 8 mm 10 mm 3/8" 1/4" 10 mm ²⁾</td> </tr> <tr> <td style="padding-right: 20px;">Blind hollow shaft</td> <td>6 mm 8 mm 10 mm 3/8" 1/4" 5 mm</td> </tr> </table>	Solid shaft, Servo flange	6 mm 8 mm 10 mm 1/4" 3/8" 6 mm ¹⁾	Solid shaft, face mount flange	6 mm 8 mm 10 mm 3/8" 1/4" 10 mm ²⁾	Blind hollow shaft	6 mm 8 mm 10 mm 3/8" 1/4" 5 mm		
Solid shaft, Servo flange	6 mm 8 mm 10 mm 1/4" 3/8" 6 mm ¹⁾								
Solid shaft, face mount flange	6 mm 8 mm 10 mm 3/8" 1/4" 10 mm ²⁾								
Blind hollow shaft	6 mm 8 mm 10 mm 3/8" 1/4" 5 mm								
Connection type	Male connector, M12, 4-pin, universal Cable, 4-wire, universal Male connector, M12, 5-pin, universal Cable, 5-wire, universal Male connector, M12, 8-pin, universal Cable, 8-wire, universal								
Communication interface	IO-Link CANopen SSI (depending on type)								
Communication Interface detail	IO-Link V1.1 / COM3 (230,4 kBaud)								
Number of steps per revolution (max. resolution)	<table border="0"> <tr> <td style="padding-right: 20px;">IO-Link, IO-Link V1.1, programmable</td> <td>4,096 (12 bit) 16,384 (14 bit)</td> </tr> <tr> <td style="padding-right: 20px;">CANopen, programmable</td> <td>16,384 (14 bit) 4,096 (12 bit)</td> </tr> <tr> <td style="padding-right: 20px;">SSI, non programmable</td> <td>4,096 (12 bit) 16,384 (14 bit) 8,192 (13 bit) 3,600 360 256 2,048 (11 bit) 512 (9 bit) 720 1,024 (10 bit)</td> </tr> <tr> <td style="padding-right: 20px;">SSI, programmable</td> <td>16,384 (14 bit) 4,096 (12 bit)</td> </tr> </table>	IO-Link, IO-Link V1.1, programmable	4,096 (12 bit) 16,384 (14 bit)	CANopen, programmable	16,384 (14 bit) 4,096 (12 bit)	SSI, non programmable	4,096 (12 bit) 16,384 (14 bit) 8,192 (13 bit) 3,600 360 256 2,048 (11 bit) 512 (9 bit) 720 1,024 (10 bit)	SSI, programmable	16,384 (14 bit) 4,096 (12 bit)
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SSI, programmable	16,384 (14 bit) 4,096 (12 bit)								
Max. resolution (number of steps per revolution x number of revolutions)	<table border="0"> <tr> <td style="padding-right: 20px;">IO-Link, IO-Link V1.1, programmable</td> <td>12 bit x 12 bit (4,096 x 4,096)</td> </tr> </table>	IO-Link, IO-Link V1.1, programmable	12 bit x 12 bit (4,096 x 4,096)						
IO-Link, IO-Link V1.1, programmable	12 bit x 12 bit (4,096 x 4,096)								

¹⁾ For adapting to 1.25 m Ecoline wire draw mechanism; only available for multiturn variants.

²⁾ For use with the adapters 2072298 and 2072295.

	14 bit x 12 bit (16,384 x 4,096)
CANopen, programmable	14 bit x 12 bit (16,384 x 4,096) 12 bit x 12 bit (4,096 x 4,096)
SSI, non programmable	12 bit x 12 bit (4,096 x 4,096) 13 bit x 12 bit (8,192 x 4,096) 14 bit x 12 bit (16,384 x 4,096) 9 bit x 12 bit (512 x 4,096) 10 bit x 12 bit (1,024 x 4,096) 8 bit x 12 bit (4,096 x 4,096) 8 bit x 12 bit (256 x 4,096) 11 bit x 12 bit (2,048 x 4,096)
SSI, programmable	14 bit x 12 bit (16,384 x 4,096) 13 bit x 12 bit (8,192 x 4,096)
Programmable/configurable	Over PLC-Engineering-Tool Over SOPAS Over handheld programming tool (depending on type)

¹⁾ For adapting to 1.25 m Ecoline wire draw mechanism; only available for multiturn variants.

²⁾ For use with the adapters 2072298 and 2072295.

Product description

AHS/AHM36 absolute encoders set standards when it comes to mechanical adaptation, communication and resistance to environmental influences. With their rotatable male connector or cable connection as well as various mounting hole patterns and adapter flanges, these encoders are suitable for nearly any application. The IO-Link, CANopen and SSI interfaces enable easy integration into various control environments. Encoder configuration can be adapted to individual needs using various tools. The rugged, reliable, fully magnetic sensor system provides a maximum resolution of 14 bits (singleturn) or 26 bits (multiturn). Due to the stainless-steel design and enclosure rating IP69K, the Inox versions are suitable for use under very harsh ambient conditions.



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winner

At a glance

- 36 mm absolute encoder with maximum 26 bits (singleturn: 14 bits multiturn: 12 bits)
- Face mount flange, servo flange, blind hollow shaft
- Rotatable male connector or cable connection
- IO-Link, CANopen, SSI interface with programmable parameterization
- Diagnostic functions
- Stainless steel (Inox versions)
- IP67 to IP69K protection class

Your benefits

- Simple mechanical installation thanks to the rotatable male connector or cable connection and various mounting hole patterns and shafts
- Easy integration into various control environments with IO-Link, CANopen and SSI interfaces
- Intelligent diagnostic functions evaluate maintenance intervals for the entire system
- Thanks to the rugged, reliable, fully-magnetic sensors, they can also be used in harsh environments
- High resistance to ambient influences due to stainless steel design and IP69K enclosure rating (Inox versions)
- Space-saving and cost-effective design
- High performance at a cost-efficient price
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Fields of application

Measures the absolute position in various industries, machines, and tools, including automated guided vehicle systems (AGV systems), industrial trucks, commercial vehicles, packaging machines, logistics applications, machine construction and medical technology.

Type code

Other models and accessories → www.sick.com/AHS_AHM36

Encoder design

S	Singleturn
M	Multiturn

Type

B	Basic
A	Advanced
I	Inox

Mechanical design ¹⁾

S	1	Solid shaft, servo flange 6 mm x 12 mm
S	9	Solid shaft, servo flange 8 mm x 12 mm
S	2	Solid shaft, servo flange 10 mm x 12 mm
S	A	Solid shaft, servo flange 1/4" x 12 mm
S	B	Solid shaft, servo flange 3/8" x 12 mm
S	3	Solid shaft, face mount flange 6 mm x 12 mm
S	5	Solid shaft, face mount flange 8 mm x 12 mm
S	4	Solid shaft, face mount flange 10 mm x 12 mm
S	8	Solid shaft, face mount flange 1/4" x 12 mm
S	7	Solid shaft, face mount flange 3/8" x 12 mm
S	C	Solid shaft, face mount flange 10 mm x 24 mm for use with adapters 2072298 and 2072295 ²⁾
S	D	Solid shaft, servo flange 6 mm x 12 mm for adapting to 1.25 m Ecoline wire draw mechanism ^{3) 4)}
B	A	Blind hollow shaft 6 mm
B	B	Blind hollow shaft 8 mm
B	C	Blind hollow shaft 3/8"
B	D	Blind hollow shaft 10 mm
B	K	Blind hollow shaft 1/4"

Communication interface

C	CANopen
Q	IO-Link
A	4.5 ... 32V, SSI, gray
P	4.5 V ... 32 V, SSI, gray, binary, programmable ⁵⁾

Connection type

C	Male connector, M12, 5-pin, universal ⁶⁾
C	Male connector, M12, 4-pin, universal ⁷⁾
C	Male connector, M12, 8-pin, universal ⁸⁾
J	Cable, 5-wire, universal, 0.5 m ^{6) 9)}
J	Cable, 4-wire, universal, 0.5 m ^{7) 9)}
J	Cable, 8-wire, universal, 0.5 m ^{8) 9)}
K	Cable, 5-wire, universal, 1.5 m ^{6) 9)}
K	Cable, 4-wire, universal, 1.5 m ^{7) 9)}
K	Cable, 8-wire, universal, 1.5 m ^{8) 9)}
L	Cable, 5-wire, universal, 3 m ^{6) 9)}
L	Cable, 4-wire, universal, 3 m ^{7) 9)}
L	Cable, 8-wire, universal, 3 m ^{8) 9)}
M	Cable, 5-wire, universal, 5 m ^{6) 9)}
M	Cable, 4-wire, universal, 5 m ^{7) 9)}
M	Cable, 8-wire, universal, 5 m ^{8) 9)}

Resolution

1 ... 4096	Increments per revolution (Singleturn encoder version, Basic type) ^{10) 11)}
1 ... 16384	Increments per revolution (Singleturn encoder version, Advanced, Inox type) ^{10) 11)}
0x0 ... 12x12	Resolution (Multiturn encoder version, Basic type) ^{11) 12)}
0x0 ... 14x12	Resolution (Multiturn encoder version, Advanced, Inox type) ^{11) 12)}
000A30	De-vice with Smart Task A30 "length measurement and trigger" (multi-turn en- IO-Link communication interface: Increments per revolution and resolution can be programmed via IO-Link master or SOPAS

- 1) Additional mechanical interfaces can be implemented using flange adapters, see attachment suggestions.
- 2) Permissible shaft load lower than specified in the technical data.
- 3) Only for Multiturn encoder versions.
- 4) Enclosure rating on shaft side always IP65.
- 5) Only for Advanced and Inox type.
- 6) CANopen communication interface.
- 7) IO-Link communication interface.
- 8) SSI communication interface, NRTL certification is only valid for operating temperatures of - 40 ° C to + 85 ° C.
- 9) The universal cable outlet is positioned so that it is possible to lay it without bends in a radial or axial direction.
- 10) See "Increments per revolution" table.
- 11) CANopen communication interface: Increments per revolution and resolution can be programmed via control or hand-held programming tool; IO-Link communication interface: Increments per revolution and resolution can be programmed via IO-Link master or SOPAS; SSI communication interface: Increments per revolution and resolution can be programmed via SOPAS or hand-held programming tool.
- 12) See "Resolution" table.
- 13) IO-Link Advanced device with additional Smart Task functionality, only available with multiturn variants.

Number of steps per revolution (more upon request)

	AHS36B / AHM36B	AHS36A/AH-M36A/AHS36I/AHM36I
Non-programmable (for SSI communication interface)	00256	00256
	00360	00360
	00512	00512
	00720	00720
	01024	01024
	02048	02048
	03600	03600
	04096	04096
	-	08192
	-	16384
Programmable (via CANopen, IO-Link and SSI communication interface, can be programmed)	00001 ... 04096	00001 ... 16384

Resolution (available upon request)

	AHS36B / AHM36B	AHS36A/AH-M36A/AHS36I/AHM36I
Non-programmable (for SSI communication interface)	08x12	08x12
	09x12	09x12
	10x12	10x12
	11x12	11x12
	12x12	12x12
	-	13x12
	-	14x12
	Programmable (via CANopen, IO-Link and SSI communication interface, can be programmed)	00x00 ... 12x12

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

WORLDWIDE PRESENCE:

Contacts and other locations –www.sick.com