MAN0844-05-EN Specifications / Installation



SmartMod <u>Digital Input/Output Module</u>

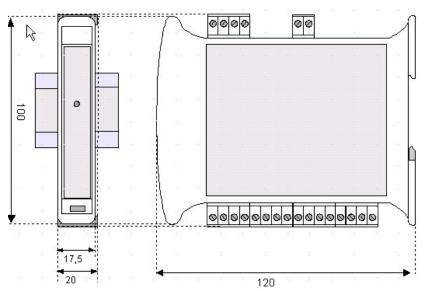
HE359DIQ512

Four 12/24V DC Inputs (neg. logic) Four Relay Outputs (2A, max)

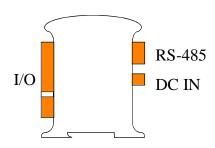


1 Specifications

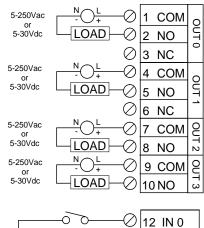
4 (1 Common)
12/24 VDC
4.7k ohms
30 VDC
10 VDC
0-3 VDC
4 (2 SPDT, 2 SPST)
2A @ 250 VAC
2A @ 30 VDC
5 VDC, 10mA
250VAC, 110 VDC
45mA @ 24Vdc, typical
Negligible
2000Vac for 60 seconds (Input/Power &
Input/Comms)
Min. 20mS - Determined by
Communications w/OCS
Screw Type, Removable
-40° to 85° Celsius
-10° to 60° Celsius
0 to 90% Non-condensing
17.5mm x 100mm x 120mm
0.69" x 3.94" x 4.72"
210g (8.4 oz.)
Modbus/RTU (binary)
RS-485 half duplex
38400 baud, N, 8, 1, no h/s
Default Modbus ID 1
1,2,3,4,5,6,8,15,16



Dimensions in inches are $0.69^{\circ}W \times 3.95^{\circ}H \times 4.72^{\circ}D$ Note: Number of I/O terminal connections varies from model to model



2 Wiring – I/O



12/24Vdc

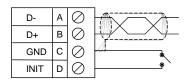
13 IN 1

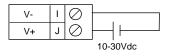
14 IN 2

15 IN 3

16 COM

Pin #	DIQ512		Pin #	DIQ512	
1	COM		9	COM	OUT 3
2	N. O.	OUT 0	10	N.O.	0013
3	N. C.				
4	COM		12	INPUT 0	
5	N. O.	OUT 1	13	INPUT 1	Note: Each
6	N. C.		14	INPUT 2	Output
7	COM	OUT 2	15	INPUT 3	COM isolated
8	N.O.	OUT 2	16	COM	





Wiring RS-485

Wiring DC IN

Notes:

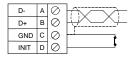
Both ends of the RS-485 network should be terminated with a 100ohm, 1/4W, 1% resistor. Many OCS controllers feature dip switches or jumpers which enable appropriate termination if the OCS is located on a network end.

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3 Init Default Setup

Communication parameters will be set to INIT default after performing the procedure:

- 1. Install jumper between INIT and GND terminals of the RS-485 port.
- 2. Apply power to Smartmod unit.
- 3. Read parameter words to see current parameters.
- 4. Write changes if necessary.



The INIT Default RS485 Settings Are:

Modbus ID = 1 Baud rate = 9600 Parity = None Stop Bits = 1 Data Bits = 8 No handshake

Note: There are 2 types of default settings possible:

- 1. Factory default as described in section 1 (Specifications)
- 2. Default after INIT as described in section 3 (INIT Default Setup)

4 Configuration DATA

SmartMod Configuration settings are mapped into Modbus Register space. This configuration data may be modified with any Modbus/RTU Master device. For convenience, Horner APG has developed a variety of Cscape application files which allow an OCS (XIe, NX, LX, QX) to act as a SmartMod configuration device. Initial configuration of SmartMod module should be done on an individual basis, since all modules come from the factory with a default Modbus ID of 1. Once each module on the network has its own unique Modbus ID, further configuration adjustments can be made with the entire network powered.

All configuration parameters listed below are stored in EPROM. This means they should not be constantly rewritten.

Conf	Configuration Parameters – Registers 40001 through 40013								
Modbus Register	Description	Min	Max	Default					
40001- 40005	Reserved								
40006	Communications Parameters	See	Table	38.4kbau d, N, 8, 1, RTU Mode					
40007	Modbus ID	1	255	1					
40008	Rx/Tx Delay (in 2mS steps)	0	255	0mS					
40009	Input Coils	Not C	a m fi m	tion Data					
40010	Output Coils		See I/O	ation Data –					
40011	Coils		See I/O	Dala					
40012	Power Up/Safe	See T	able	0					
40013	Watchdog Timer (in 0.5s steps)	0	255	10(5 sec)					

Red	ister 4000)6 (Comi	nunications	Paramet	ers) Rit I	Definition	1
Bits 15 - 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Unused	Mode	F	Parity	Data Bits	E	Baud Rat	е
	0 =	Value	Meaning	0 = 7	Value	Mea	aning
	ASCII	0	Mark	Data	0	1200	baud
	Mode	1	Even	Bits	1	2400	baud
	1 =	2	Odd	1 = 8	2	4800	baud
	RTU	3	Space	Data	3	9600	baud
	Mode			Bits	4	1920) baud
					5	38400) baud
					6, 7	Uni	used

NOTE:

Data bits number is ignored, in ASCII mode it is fixed at 7 and in RTU mode it is fixed to 8. In RTU mode the parity bit is ignored (parity is fixed at NONE).

	Register 40012 (Power Up/Safe) Bit Definition									
Bit 15-12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 4-7	Bit 3	Bit 2	Bit 1	Bit 0	
Unused	Out 3	Out 2	Out 1	Out 0	Unused	Out 3	Out 2	Out 1	Out 0	
		PowerU	p Value				Safe	Valve		

When the device is tuned-on (PowerUp) and in case of watchdog alarm (Safe), the outputs are automatically forced to the value specified in this register. Each bit corresponds to an output, as shown in the table.

- Manufacturer default: 0

5 Input/Output DATA

SmartMod Digital I/O data utilizes both Modbus Registers (40009-40011) and Coils (1-35). It is possible to access all data using Registers only, because the Coils data can be accessed through Registers.

The following tables list all Modbus I/O data available.

	Register 40009 Definition (Mirror of Digital Input Coils)															
	This register shows digital inputs state (0 = OFF, 1 = ON).															
The same					ne coil	s table	e, of v	which	n this r	registe	ris a	mirror.				
These valu	ies are	Read	d Only	١.												
Bit	15	15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0														
Descr.	Lo	w Ris	e Late	ch		Inpu	ut			Sy	nc.		Hiç	jh Ris	e Late	ch
Channel	3	3 2 1 0 3 2 1 0 3 2 1 0 3 2 1 0														
Coil	8	7	6	5	4	3	2	1	16	15	14	13	12	11	10	9

	Register 40010 Definition (Mirror of Digital Output Coils)															
This regist	This register shows digital outputs state (0 = OFF, 1 = ON).															
The same	values	s can	be rea	d by t	he coi	ls table	e, of w	hich tl	his re	gister	is a m	irror.				
These value	ues ar	e Rea	d/Writ	e.												
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Output	Output 3 2 1 0															
Coil	-	-	-	•	20	19	18	17	-	-	-	-	•	•	-	-

			Regis	ster 40	0011 [Definit	ion (N	/lirror	of Wa	atchdo	og Co	ils)				
	This register shows digital state of watchdog coils (0 = OFF, 1 = ON). These values are Read/Write .															
Bit	15	24	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Coil	-	-	-	-	•	35	34	33	-	-	•	-	-	-	-	-

	I/O Register Data Summary (Registers 40009-40011)								
Modbus Register	Description	Access	Bits 0-7 & 12-15	Bit 11	Bit 10	Bit 9	Bit 8		
40009	Mirror of Input Coil Data	Read-only	unused	In 3	ln 2	ln 1	In 0		
40010	Mirror of Output Data	Read/Write	unused	Out 3	Out 2	Out 1	Out 0		
40011	Mirror of WatchDog Data	Read/Write	unuse	ed	PwrUp Event	W.D.* Event	W.D.* Enbld		

* W.D. - Watchdog

	Modbus Coil Data									
Modbus Coil	Description	Access	Watchdog Event & Power-up Event Operation							
00001	Input 0	Read-only								
00002	Input 1	Read-only								
00003	Input 2	Read-only	If Coil 33 (Watchdog Enabled) is							
00004	Input 3	Read-only	set, Coil 34 (Watchdog Event) will							
0005- 00016	Reserved*		set if the Watchdog Timeout value is exceeded. The Watchdog Timeout value is set in Register							
000017	Output 0	Read/Write	40013. When set, Coil 34 can be							
000018	Output 1	Read/Write	reset by the controller when normal							
000019	Output 2	Read/Write	communications resumes.							
000020	Output 3	Read/Write								
00021- 00032	Reserved*		The Power-up Event (Coil 35) is set every time the power is applied. It							
00033	Watchdog Enabled	Read/Write	can be cleared by the controller if							
00034	Watchdog Event	Read/Write	desired.							
00035	Power-up Event	Read/Write								

*See definition of registers 40009 and 40010 above for more information.

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6 Watchdog

The module has been provided with a Host Watchdog timer which, when it is enabled, issues an alarm event each time the communication between the module and the host is inactive for a period time greater than the programmed one (40009).

When the alarm is activated, the values of the outputs are automatically converted to the preset safety values to avoid damage to the system in case of a fault occurring. Also, under the alarm condition the green LED on the front of the module blinks and the "Watchdog Event" coil is forced to 1. There is also a Module Watchdog timer that monitors the internal CPU work and activates when the CPU doesn't function correctly.

After the reset, all outputs will assume their initial default value ("power up value"), this may be different to the output value after the reset.

Register 40013 Definition

The Watchdog Timeout value is set in Modbus register 40013 (Resolution of 0.5s)

Coil 00033	Coil 00034	Coil 00035					
Watchdog Enabled	Watchdog Event	Power-up Event					
	0 = Input Disabled						
1 = Input Enabled							

If Coil 33 (Watchdog Enabled) is set, Coil 34 (Watchdog Event) will set if the Watchdog Timeout value is exceeded.

When set, Coil 34 can be reset by the controller when normal communications resumes.

The Power-up Event (Coil 35) is set every time the power is applied. It can be cleared by the controller if desired.

7 Sync

The Sync function is performed by a command sent to all devices connected on the network. When the devices receive the Sync command, all Input states are saved in the relative register. Doing this, it is possible to read the value of all inputs at the Sync command time.

To send the Sync command, write the value 10 in the "Test" register (40001) and send to node ID 255

NOTE: The sync values are not saved in EPROM.

When the device receives the Sync command, the actual input values in coils 13-16 are saved in register 40009 bits 4-7, channel by channel, to be read at a following time.

Coil	Register 40009 Corresponding Bit	Function
13	4	SYNC INPUT VALUE # 0
14	5	SYNC INPUT VALUE # 1
15	6	SYNC INPUT VALUE # 2
16	7	SYNC INPUT VALUE # 3

8 LED Indicator

LED	COLOUR	STATE	DESCRIPTION
POWER	Green	ON	Device Powered
		OFF	Device Not Powered / Incorrect RS485 Cabling
		Fast Blink	Communication in progress/ (blink frequency depends on baud rate)
		1 Second	Watch-dog Alarm Condition
		Blink	(See Section 6 above)

The LED is located on the front of the model.

9 Implemented Modbus Functions

Function	Code		
01	Read multiple coils (0xxxx bank)		
02	Read multiple coils (1xxxx bank)		
03	Read multiple registers (4xxxx bank)		
04	Read multiple registers (3xxxx bank)		
05	Write single coil		
06	Write single register		
15	Write multiple coils		
16	Write multiple registers		
08	Diagnostic		

For DIQ_512 SmartMod modules, bank 0xxxx is a mirror of bank 1xxxx, as 3xxxx is a mirror of 4xxxx i.e. the first register can be read independently as 30001 (with the function 04) or 40001 (with the function 03)

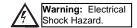
10 Installation / safety

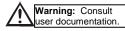
Warning: Remove power from the OCS controller, CAN port, and any peripheral equipment connected to this local system before adding or replacing this or any module.

- All applicable codes and standards should be followed in the installation of this product.
- Shielded, twisted-pair wiring should be used for best performance.
- Shields may be terminated at the module terminal strip.
- In severe applications, shields should be tied directly to the ground block within the panel.
- Use the following wire type or equivalent: Belden 8441.

For detailed installation and a <u>handy checklist</u> that covers panel box layout requirements and minimum clearances, refer to the hardware manual of the controller you are using.

When found on the product, the following symbols specify:





11 Troubleshooting Tips

If not communicating

- Verify that the wiring is correct
 - Pin 1 on the XL series serial ports is RS-485 positive (+) and is connected to positive (+)
 - Pin 2 on the XL series serial ports is RS-485 negative (-) and is connected to negative (-)
- If the ground pin is not being used, verify that only one device on the network is supplying bias. This is set from the system menu on the XL series controllers.
- Tie the INIT pin to GND then power cycle the SmartMod. Then attempt to communicate with it at the default parameters
- If using the INIT settings, verify with an ohm meter that the jumper is shorted to GND.
 Then try power cycling the SmartMod unit again.

If any I/O seems unresponsive

- Verify the Modbus address that you are polling e.g. 40009 (command of 3, 6, or 16 offset 00008)
- Verify any registers from the device that may affect the I/O. These will vary between modules. For example, enable, type selection or raw value.

12 Technical support

Technical Support at the following locations:

North America: Europe:

Tel: 317 916-4274 Tel: +353-21-4321266 Fax: 317 639-4279 Fax: +353-21-4321826

Web: http://www.heapg.com
Web: http://www.horner-apg.com
Email: tech.support@horner-apg.com

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