

MAX48 INTEGRATED CYLINDER POSITION MEASUREMENT FOR MOBILE MACHINES



Linear encoders

INTEGRATED CYLINDER POSITION MEASUREMENT FOR MOBILE MACHINES



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Product description

The MAX48 linear encoder enables non-contact, completely integrated and absolute position measurement in hydraulic cylinders. Suitable for use under extreme ambient and operating conditions in applications in mobile machines. The innovative technology of magnetostriction offers high reliability,

At a glance

- Measuring range: 50 to 2,500 mm (1 mm steps), typical resolution 0.1 mm
- Analog, CANopen, SAE J1939 and PWM interfaces are available
- Pressure-resistant housing, designed for hydraulic operating pressure of up to 400 bar

Your benefits

- Magnetostriction: Reliable, safe and wear-free
- 100% mechanical and electrically compatible with existing cylinder constructions
- Space-saving installation: Better utilization of the piston stroke in tight installation space of the cylinder

expanded diagnostic functions and well as a considerable reduction in operating costs. The 48 mm housing can be easily installed in the existing cylinder construction. All in all, linear encoders from SICK impress with their attractive cost-benefit ratio.

- High operating temperature (electronics) up to +105 °C
- Fluid temperature (hydraulic oil) up to max. +95 °C
- Compact dimensions: 10 mm installation space, 30 mm damping zone
- Position magnet does not need a spacer disk
- Extremely stable signal behavior and very good EMC properties: Resistant to extreme electrical influences, such as radiated or coupled faults in the on-board power supply
- Status monitoring: Monitoring of piston strokes, operating hours and max. oil temperature provides a statement about the cost-optimized operation of the machine
- Favorable cost-benefit ratio

www.sick.com/MAX48

For more information, simply enter the link or scan the QR code and get direct access to technical data, CAD design models, operating instructions, software, application examples, and much more.



Fields of application

Mobile work equipment

- Steering cylinder and spring systems
- · Lifting and press cylinders on garbage trucks
- Stroke, swivel and tilt cylinders on telescopic handlers
- Support cylinders on work platforms
- Cutting system adjustment, steering assistance
- Loading crane monitoring, boom cylinders
- Gripper monitoring field on container cranes

Detailed technical data

General notes

Note

Accessories not included with delivery, please order seperately.

Performance

	Analog	PWM	Digital
Measured values	Position		Position, speed
Measuring range			
Position (F.S.)	50 2,500 mm 1)		
Speed	-		0 1,000 mm/s
Unusable range			
Nullzone	30 mm		
Dampingzone	30 mm, 36 mm, 63 mm (depe	nding on type)	
Switch-on time	< 250 ms		
Measuring frequency (internal)	2 ms		1 ms
Transmission rate (cycle time)	Continuous analog output signal	Depending on type, PWM frequency	-CANopen (0 65,535 ms) Factory setting: 0 ms (transmission stopped) -SAE J1939: 20 ms
Setting point tolerance			
(Zero point and F.S.)	≤ ± 1 mm		
Resolution	Typ. 0.1 mm (noise-free)		
Hysteresis	± 0.1 mm		
Repeatability	Typ. ± 0.2 mm		
Linearity (in the operational status)	Typ. ± 0.25 mm (measuring ra Typ. ± 0.04% F.S. (measuring r	•	
Temperature drift			
Self-heating of the electronics (Warm-up phase)			
Operational status (Hydraulic oil at operating temperature)			
MTTFd	69 years (EN ISO 13849-1) 3) 4)		
1) E.S Eull Scale (Measuring range)			

¹⁾ F.S. = Full Scale (Measuring range)

 $^{\scriptscriptstyle 2)}$ Increase in oil temperature by 40°C during operation.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature of electronic 60°C, frequency of use 8760 h/a.

⁴⁾ Every second failure of an electronic component is regarded as a dangerous failure.

Interfaces

	Analog	PWM	Digital
Communication interface detail	Voltage / current	PWM	CANopen / SAE J1939
Voltage output	0.25 4.75 V 0.50 4.50 V 0.50 9.50 V 1.00 9.00 V 9.50 0.50 V 9.00 1.00 V 4.75 0.25 V 4.50 0.50 V	-	
Current output	4.00 20.00 mA 20.00 4.00 mA	-	
Bus protocol	-		CANopen CiA DS-301
Device profile	-		CANopen CiA DS-406
Network Management Protocol	-		SAE J1939-81
Application Layer	-		SAE J1939-71
Puls width	-	05% 95% 10% 95% 15% 85% 20% 80% 25% 75%	-
Frequency	-	250 Hz 300 Hz 400 Hz 500 Hz	-

Electrical data

	Analog	PWM	Digital
Connection type	M12 connector, 4-pin Connecting cable, 3-wire		M12 connector, 5-pin
Supply voltage			
12 V DC	$8 \ \ 16 \ V \ DC^{\ 1)}$	-	
24 V DC	8 36 V DC	8 36 V DC	
Residual ripple	< 1% S-S		
Power consumption			
12 V DC	\leq 0.75 W ¹⁾	-	
24 V DC	\leq 1.25 W ²⁾	-	
24 V DC	≤ 0.75 W		
Current consumption			
12 V DC	≤ 60 mA ¹⁾	-	
24 V DC	\leq 50 mA ²⁾		
24 V DC	≤ 30 mA		
Load resistance			
Voltage signal	$RL \ge 10 k\Omega$	-	
Current signal	$100 \Omega \leq RL \leq 500 \Omega$	-	
Bustermination	-		120 Ω
Switch-on current			
12 V DC	Typ. 2.5 A/ 50 μs	-	
24 V DC	Typ. 5.0 A/ 50 μs		

	Analog	PWM	Digital
Over voltage protection			
12 V DC	\leq 18 V at all poles during the switch-on process (60 s) \leq 24 V to GND during the switch-on process (60 s)		
24 V DC	\leq 36 V at all poles during the switch-on process (60 s) \leq 48 V to GND during the switch-on process (60 s)		
Reverse polarity protection	≤ 36 V (at all poles) (ISO 16750-2)		
Insulation resistance	R _{iso} ≥ 10 MΩ, 60 s (ISO 16750-2)		
Dielectric strength	500 V DC (0 V against housing	(ISO 16750-2)	

 $^{_{1)}}$ Valid for voltage outputs 0.50 ... 4.50 V; 4.50 ... 0.50 V; 0.25 ... 4.75 V ; 4.75 ... 0.25 V

 $^{\scriptscriptstyle 2)}$ Valid for current output 4 ... 20 mA; 20 ... 4 mA

Mechanical data

	Analog	PWM	Digital
Dimensions			
Construction size	48f7 mm (for installation in dril	l hole 48H8)	
Ø pressure pipe	10 mm		
Ø O-ring	Ø 40.87 mm x 3.53 mm		
Ø support ring	Ø 48 mm x Ø 42.6 mm x 1.4 mi	n	
M12 flange type S	Construction DM 20x20 mm - h	ole pattern 14 mm (EN 61076-	2-101)
M12 flange type L	Construction DM 24x24 mm - hole pattern 17 mm (EN 61076-2-101)		
M12 connector (stranded wires)	60 240 mm (depending on type)		
Connecting cable / stripped wires	Ø 5.0 mm / Ø 1.4 mm 300 10.000 mm (depending 3 x 0.38 mm² (AWG22)	on type)	
Material			
Electronics enclosure	Stainless steel 1.4305, AISI 30	3	
Pressure pipe	Stainless steel 1.4404, AISI 31	6L	
O-ring	NBR 70		
Support ring	PTFE		
Connection inlay	Glass fiber reinforced polyamid	e, nickel-/gold-plated brass cor	tacts
M12 flange	Nickel-plated brass with O-ring	(NBR)	
Connecting cable / stranded wire	PUR / PVC		

Ambient data

	Analog	PWM	Digital
EMC	EU Directive 2014/30/EU CE m	arking	
Generic standards	EN 61000-6-2 and EN 61000-	6-3	
Agricultural and forestry machinery Construction machinery	ISO 14982 EN 13309/ISO 13766		
Transient pulses	ISO 7637-2		
ESD (air and contact discharge)	EN 61000-4-2, ISO/TR 10605		
Enclosure rating			
Housing without electrical connection Housing with connecting cable	IP67 (EN 60529) IP67 (EN 60529)		
M12 connector	IP69k (ISO 20653)		
Temperature			
Operating temperature range (electronics)	-40 °C +105 °C $^{1)}$		
Ambient temperature (fluid)	-30 °C +95 °C ²⁾		
Storage temperature range	-20 °C +65 °C ^{3) 4)}		
Permissible relative humidity	90 % (Condensation not permit	ted)	
Resistance to shocks	Fall test in acc. with IEC 60068 100 g, 11 ms (Single shock in a 50 g, 11 ms (Continuous shock		s in acc. with IEC 60068-2-27)
Resistance to vibration Sinus Sinus noise Noise (resonance points excluded)	20 g, 24 h / spatial axis, 55 18 g (r.m.s), 36 h / spatial axis 20 g (r.m.s), 48 h / spatial axis	10 2,000 Hz (IEC 60068-2-8	
Nominal operating pressure (P_N)	400 bar		
Max. overload operation pressure $(P_N x 1.2)$	480 bar		
Max. test pressure in cylinder ($P_N x 1.5$)	600 bar		

¹⁾ Considered self-heating caused by continuously electrical operation with applied supply voltage.

²⁾ Due to permissible temperature loads of O-ring seals, hydraulic oil and the temperature-dependent signal quality of the position magnet.

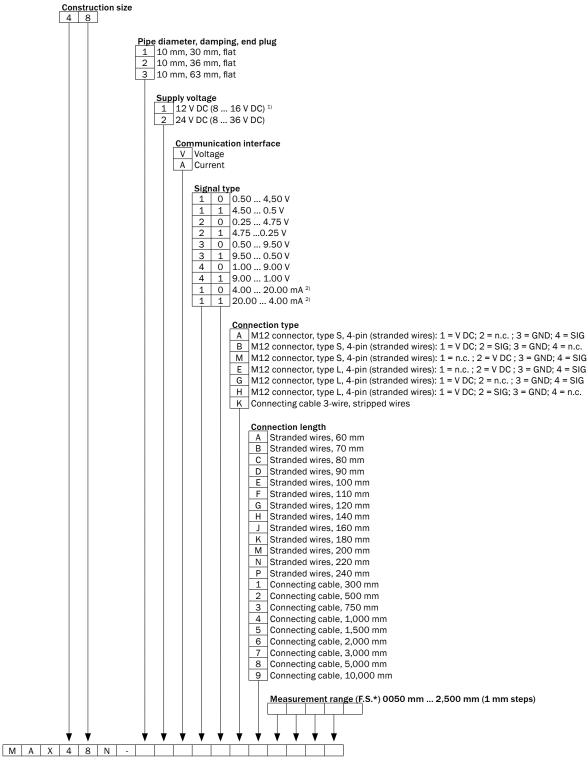
³⁾ Relative Humidity 55 %

⁴⁾ Due to the dry storage of the O-ring when not installed (not wetted by hydraulic oil).

For details of applied tests and descriptive standards, please see document 8021473.

Typecode

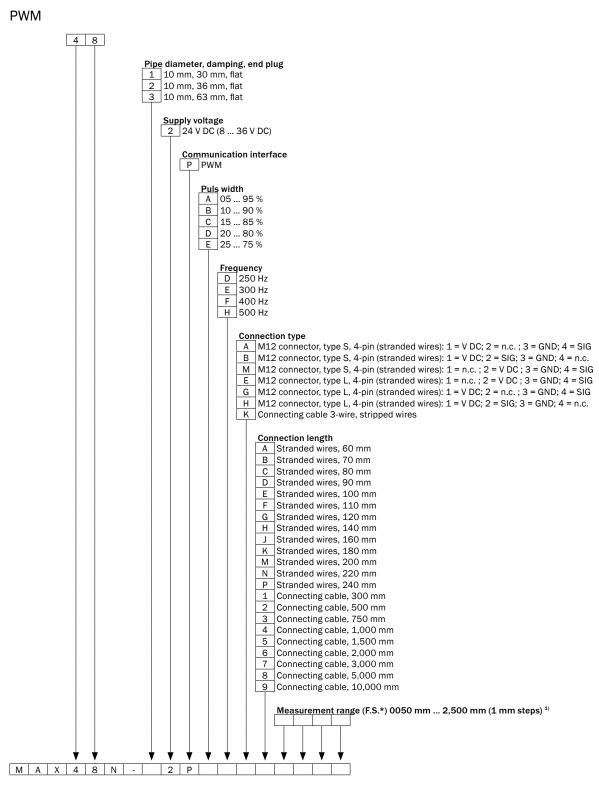
Analog



 $^{\mbox{\tiny 1)}}$ Only in combination with voltage output (signal type V10, V11, V20, V21)

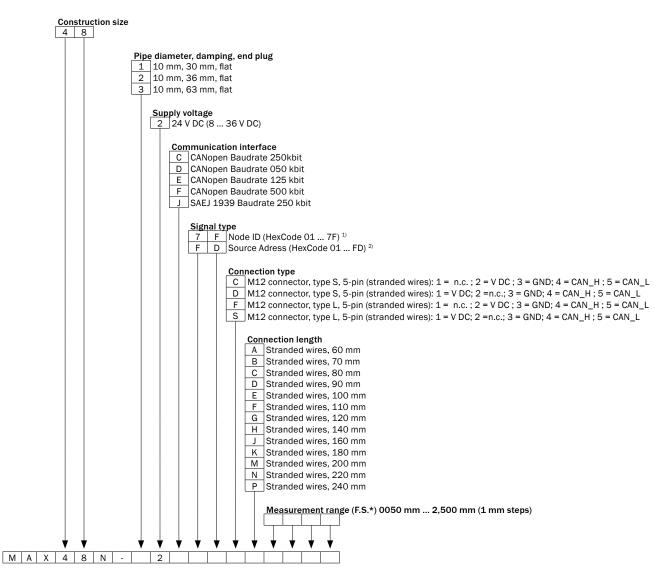
²⁾ Only in combination with communication interface A

* Full Scale (measuring range end value)



* Full Scale (measuring range end value)

Digital

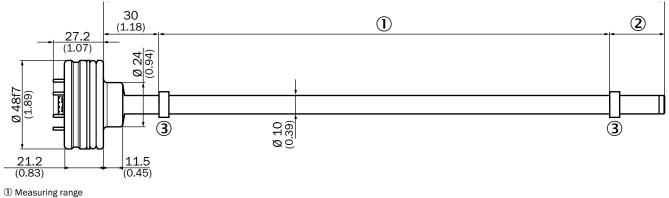


¹⁾ Only in combination with communication interface CANopen ²⁾ Only in combination with communication interface SAEJ 1939

* Full Scale (measuring range end value)

Dimensional drawing

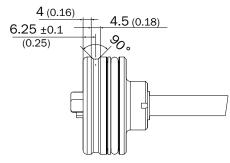
MAX48



② Damping zone

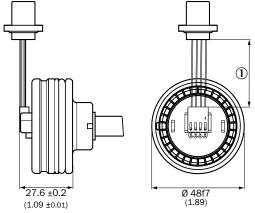
③ Position magnet





Encoder with electrical connection

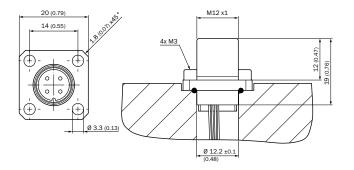
M12 connector (Analog/ PWM/ Digital interface)



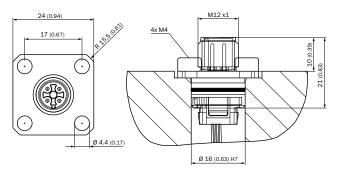
1 Stranded wires length (depending on type)

Encoder with electrical connection

M12 connector type S/ flange - axial seal



M12 connector type L/ flange - radial seal

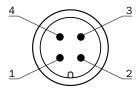


PIN assignment

M12 (4-pin for Analog/ PWM interface)

PIN assignment A (Type S)

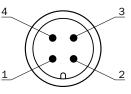
PIN assignment G (Type L)



VDC
N. C.
GND
Signal

PIN assignment B (Type S)

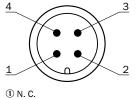
PIN assignment H (Type L



VDC
Signal
GND
N. C.

PIN assignment (Type S)

PIN assignment E (Type L)

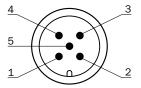


N. C.
VDC
GND
Signal

M12 connector (5-pin for Digital interface)

PIN assignment D (Type S)

PIN assignment S (Type L)



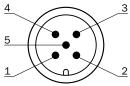
1	VDC
2	N.C.
3	GND

4	CAN _H
---	------------------

 $\odot CAN_L$

PIN assignment C (Type S)

PIN assignment F (Type L)

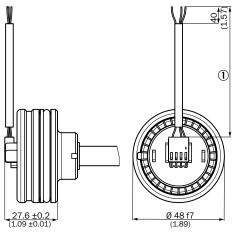


N.C.
VDC
GND
CAN_H
CAN_L

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Encoder with electrical connection

Connecting cable 3-wire (Analog/ PWM interface)

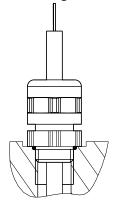


(1) Connecting cable length (depending on type)

Wire color	Terminal	Wire colo	r Terminal
brown	V DC	brown	V DC
blue	GND	blue	GND
black	SIG (V)	white	SIG (mA)

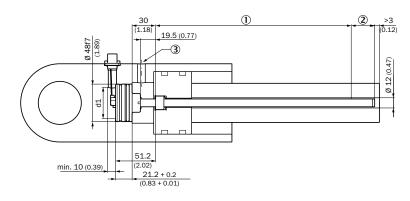
Encoder with electrical connection - connecting cable

Cable fitting mount



Assembly note

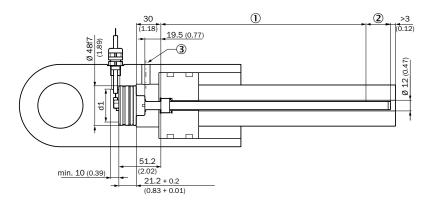
IN-cylinder assembly



1 Measuring range

- ② Damping zone
- ${}^{\textcircled{3}}$ Hydraulic port

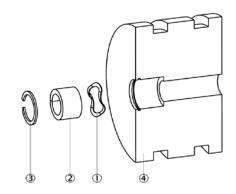
Please observe the information in the operating instructions (8021473) (d: $32 \le d \le 40$).



- ① Measuring range
- ② Damping zone
- ③ Hydraulic port

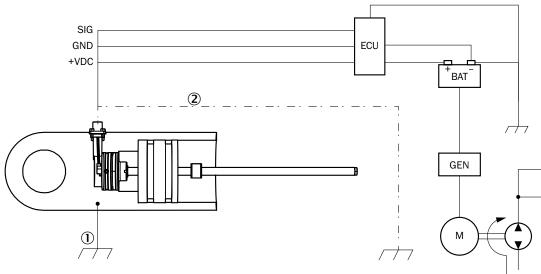
Please observe the information in the operating instructions (8021473) (d: $32 \le d \le 40$).

Installation of the position magnet



Corrugated spring washer
Position magnet
Circlip

④ Piston



Connection diagram

Chassis GND
Cable shielding (optional)

Accessories

Mounting systems

Flanges

Flange plates

Figure	Brief description	Packaging unit	Туре	Part no.
	1	BEF-FA-M12L-01	2117510	
69	Flange for M12 male connector, type L square flange (24 mm x 24 mm) with axial seal, nickel-plated brass	5	BEF-FA-M12L-05	2117511
	10	BEF-FA-M12L-10	2117512	
		1	BEF-FA-M12S-01	2117507
Flange for M12 male connector, type S square flange (20 mm x 20 mm) with axial seal, nickel-plated brass	5	BEF-FA-M12S-05	2117508	
5	x 20 milli with axial soul, moner plated blass		BEF-FA-M12S-10	2117509

Dimensional drawings → page 16

Other mounting accessories

Others

Figure	Brief description	Packaging unit	Туре	Part no.
		1	BEF-MK-SR-01	2116437
\bigcirc	Circlip for installing the position magnets in the piston of the	5	BEF-MK-SR-05	
	hydraulic cylinder, stainless steel 1.4300 / SAE 302	10	BEF-MK-SR-10	2116439
		50	BEF-MK-SR-50	2116440
		1	BEF-MK-WF-01	2116431
	Corrugated spring washer for installing the position magnets in the piston of the hydraulic cylinder, stainless steel 1.4568	5	BEF-MK-WF-05	2116432
/ SAE 631		10	BEF-MK-WF-10	2116433
	50	BEF-MK-WF-50	2116435	

Dimensional drawings -> page 16

Connection systems

Plug connectors and cables

Other connectors and cables

Figure	Brief description	Packaging unit	Туре	Part no.
R.	Head A: M12 Cable: shielded Cable gland with M12 x 1.5 connection thread, polyamide V0 terminal insert in accordance with UL94, NBR O-ring, NBR molded seal, WAF 14	1	BEF-EA-M12-S	2117513

Dimensional drawings → page 16

Further accessories

Magnets

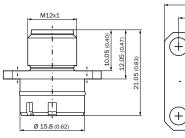
Figure	Brief description	Packaging unit	Туре	Part no.
0	Position magnet for magnorestrictive linear encoder, Ø 17.4 mm	1	MAG-0-174-01	2112714
		5	MAG-0-174-05	2112713
		10	MAG-0-174-10	2115045
		50	MAG-0-174-50	2112711

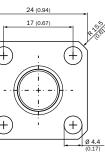
Dimensional drawings -> page 16

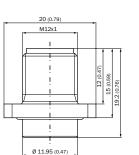
Dimensional drawings for accessories (Dimensions in mm (inch))

Flanges

Square flange type L (BEF-FA-M12L-xx)

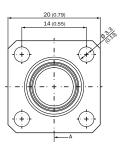






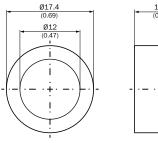
0.94

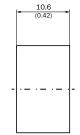
Square flange type S (BEF-FA-M12S-xx)



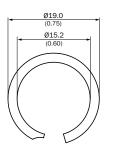
Other mounting accessories

Position magnet (MAG-0-174-xx)

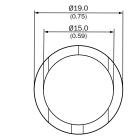


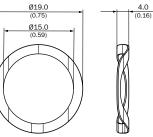


Circlip (BEF-MK-SR-xx)



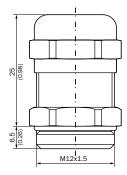
Spring washer (BEF-MK-WF-xx)





Plug connectors and cables

Cable gland (BEF-EA-M12-S



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